

5/26/04

lecture 4

Spatial patterns / waves

▲ Spatial patterns in development

(a) waves in fly embryo

(b) diffusion equation

random walk / diffusion

a simple solution of 1D diffusion eq.

time scale, no wave possible

(c) reaction-diffusion eq.

Fisher-Kolmogoroff eq.

the derivation of Fisher

{ logistic growth

{ spread of disease

auto catalysis

Analysis of Fisher-Kolmogoroff eq.

traveling wave solution

phase plane analysis / minimum speed

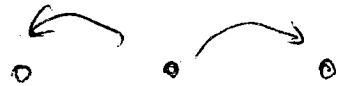
initial condition dependence

shape of the wave

simple argument on speed

diffusion / random walk

random walker in 1D



each step size ℓ

N steps

typical distance travelled d .

$$X = x_1 + x_2 + \dots + x_N$$

where $x_i = \pm \ell$ equal prob.

$$\bar{X} = \bar{x}_1 + \bar{x}_2 + \dots + \bar{x}_N = 0$$

$$\begin{aligned}\bar{x^2} &= (\bar{\sum x_i})^2 = \bar{\sum_i} \bar{\sum_j} x_i x_j \\ &= N \bar{\sum_i} x_i^2 = N \ell^2\end{aligned}$$

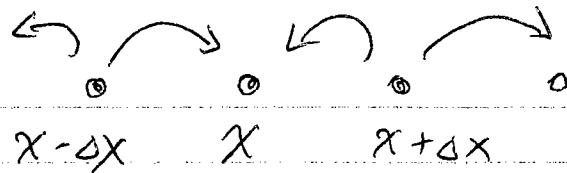
typical distance

$$d = \sqrt{\bar{x^2}} = N^{1/2} \ell$$

diffusion eq.

1D lattice, population

$u(x, t)$ particle density
at position x
and time t



$$u(x, t + \Delta t) = \frac{1}{2} [u(x + \Delta x, t) + u(x - \Delta x, t)]$$

$$\begin{aligned} &= u(x, t) + \frac{\partial u}{\partial t} \Delta t \quad \text{partial derivative} \\ &\quad \text{hold } x \text{ fixed} \\ &= u(x, t) + \frac{\partial u}{\partial x}(x, t) \Delta x + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} \Delta x^2 + \\ &\quad + u(x, t) - \frac{\partial u}{\partial x}(x, t) \Delta x + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} \Delta x^2 \\ &= \frac{1}{2} \cdot 2 u(x, t) + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} \Delta x^2 \end{aligned}$$

$$\frac{\partial u}{\partial t} = \frac{\Delta x^2}{2 \Delta t} \frac{\partial^2 u}{\partial x^2} \quad \text{define}$$

$$D = \frac{\Delta x^2}{2 \Delta t}$$

\downarrow
diffusion coefficient

$$\boxed{\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}}$$

diffusion equation

can also be obtained by using

$$\text{Fick's Law} \quad J = -D \frac{\partial u}{\partial x}$$

and mass conservation

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} J = 0$$

△ existence of diffusion coefficient

$$D = \frac{\Delta X^2}{2\Delta t} \quad \Delta t \rightarrow 0 \quad \text{exist}$$

when $\tau \ll \Delta t \ll t$

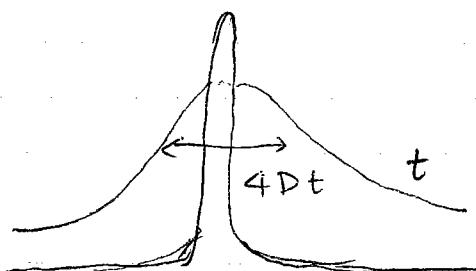
where τ is the microscopic time scale on which particle change its direction due to random collision

l : typical length particle travel before changing direction

$$\Delta X^2 = N l^2, \quad N = \frac{\Delta t}{\tau}$$

$$\Delta X^2 = \frac{\Delta t}{\tau} l^2, \quad \frac{\Delta X^2}{\Delta t} \rightarrow \frac{l^2}{\tau}$$

△ a typical solution of 1D diffusion eq. $t=0$



start

with concentration concentrated at $x=0$

$$u(x, t=0) = \delta(x)$$

what's the solution $u(x, t)$?

dimensional analysis

length scale: $\begin{cases} x \\ \sqrt{Dt} \end{cases}$

$$u(x, t) = \frac{1}{\sqrt{Dt}} g\left(\frac{x}{\sqrt{Dt}}\right) = \frac{1}{\sqrt{Dt}} g(z)$$

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} \quad z = \frac{x}{\sqrt{Dt}}$$

↓

$$-\frac{1}{2}t^{-\frac{3}{2}}\frac{1}{\sqrt{D}}g(z) + \frac{1}{\sqrt{Dt}}g'(z)\frac{x}{\sqrt{D}}(-\frac{1}{2}t^{-\frac{3}{2}})$$

$$= D \cdot g''(z) \frac{1}{Dt} \cdot \frac{1}{\sqrt{Dt}}$$

$$g''(z) + \frac{1}{2}g(z) + \frac{1}{2}zg'(z) = 0$$

$$\frac{d}{dz} \left[g'(z) + \frac{1}{2}zg(z) \right] = 0$$

$$g'(z) + \frac{1}{2}zg(z) = A \rightarrow \text{const}$$

$$z=0, g'(z)=0, \quad (\text{symmetric})$$

$$\hookrightarrow A=0$$

$$\frac{g'(z)}{g(z)} = -\frac{1}{2}z$$

$$g(z) = \text{const} \cdot e^{-\frac{z^2}{4}}$$

$$u(x, t) \propto \frac{1}{\sqrt{Dt}} e^{-\frac{x^2}{4Dt}}$$

normalization $\int_{-\infty}^{+\infty} u(x, t) dx = 1$

$$u(x, t) = \frac{1}{\sqrt{4\pi Dt}} e^{-\frac{x^2}{4Dt}}$$

given time t ,

particle diffuse to a region

of size $\sim \sqrt{Dt}$

can be obtained
from random
walker
model
+ central
limit theorem

time scale estimate

given length L

time it takes to diffuse

$$t \sim \frac{L^2}{D}$$

$$D \sim 0.1 \times 10^{-9} \text{ m}^2/\text{s}, \quad L \sim 1 \text{ mm}$$

fly egg

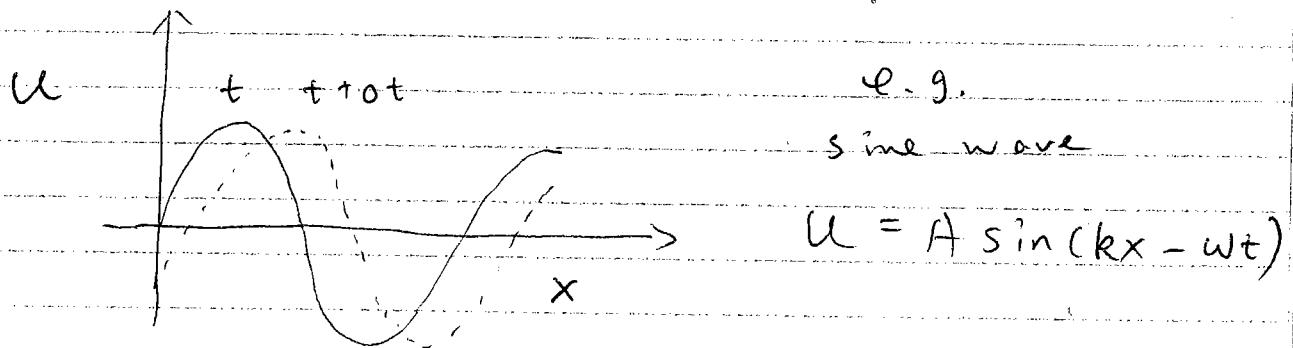
for Ca in cytoplasm

$$t \sim \frac{(1 \text{ mm})^2}{0.1 \times 10^{-9} \text{ m}^2/\text{s}} \sim 3 \text{ hours}$$

in general, diffusion is too slow
for signal propagation

- (A) diffusion eq does not have traveling wave solution
- a general traveling wave

$$u(x, t) = u(z) = u(x - ct)$$



$$\text{if } u = u(x - ct)$$

$$D \frac{d^2 u}{dz^2} + \rho \frac{du}{dz} = 0$$

$$u = A + B e^{-\frac{c}{D} z}$$

to be bounded as $z \rightarrow -\infty$

$$B = 0$$

u is uniform everywhere

reaction-diffusion eq.

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} + f(u) \xrightarrow{\substack{\text{growth} \\ \text{term}}}$$

△ Fisher - kolmogoroff eq.

Advance of advantageous genes

allele A_1 : p advantageous
 A_2 : q

Genotype $A_1 A_1$ $A_1 A_2$ $A_2 A_2$

p^2 $2pq$ q^2

relative fitness 1 $1 - \frac{s}{2}$ $1-s$

freq. after selection $\frac{p^2}{\bar{w}}$ $\frac{2pq(1-\frac{s}{2})}{\bar{w}}$ $\frac{q^2(1-s)}{\bar{w}}$

$$\bar{w} = p^2 + 2pq(1-\frac{s}{2}) + q^2(1-s)$$

↑
normalization = $1 - pq s - q^2 s$

after selection

$$p' = \frac{p^2}{\bar{w}} + \frac{pq(1-\frac{s}{2})}{\bar{w}}$$

($A_1 A_2$ has
only one
 A_1 allele)

$$\Delta p = p' - p$$

$$= \frac{p - \frac{pq s}{2}}{1 - pq s - q^2 s} - p \approx \frac{1}{2} pq s$$

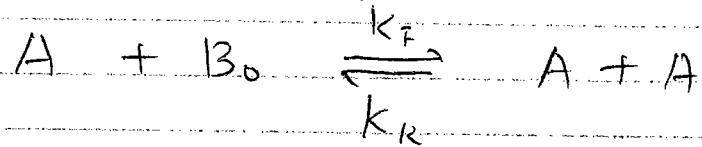
$$\frac{dp}{dt} = \frac{s}{2st} p(1-p) \equiv kp(1-p)$$



$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} + ku(1-u)$$

△ Fisher eq. in other context

* auto-catalysis



$$\begin{aligned}\frac{d[A]}{dt} &= k_F [A][B_0] - k_R [A]^2 \\ &= k_F [A][B_0] \left(1 - \frac{k_R [A]}{k_F [B_0]}\right)\end{aligned}$$

$$u = \frac{[A]}{[B_0]} \frac{k_R}{k_F}$$

$$\begin{aligned}\frac{du}{dt} &= k_F[B_0] u (1-u) \\ &\equiv ku(1-u)\end{aligned}$$

* logistic growth
species invasion

$$\frac{dn}{dt} = kn \left(1 - \frac{n}{N}\right) - \text{growth}$$

disease propagation total

$$\frac{ds}{dt} = \alpha SH = \alpha S(T-s)$$

Sick Healthy

(a) behavior of Fisher-Kolmogoroff eq.

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} + ku(1-u)$$

dimensions: $[K] = \frac{1}{[T]}$

$$[D] = \frac{[L]^2}{[T]}$$

$$\left[\sqrt{\frac{D}{K}} \right] = [L]$$

$$t' \Rightarrow kt$$

$$x' \rightarrow x \sqrt{\frac{K}{D}}$$

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + u(1-u)$$

traveling wave solution

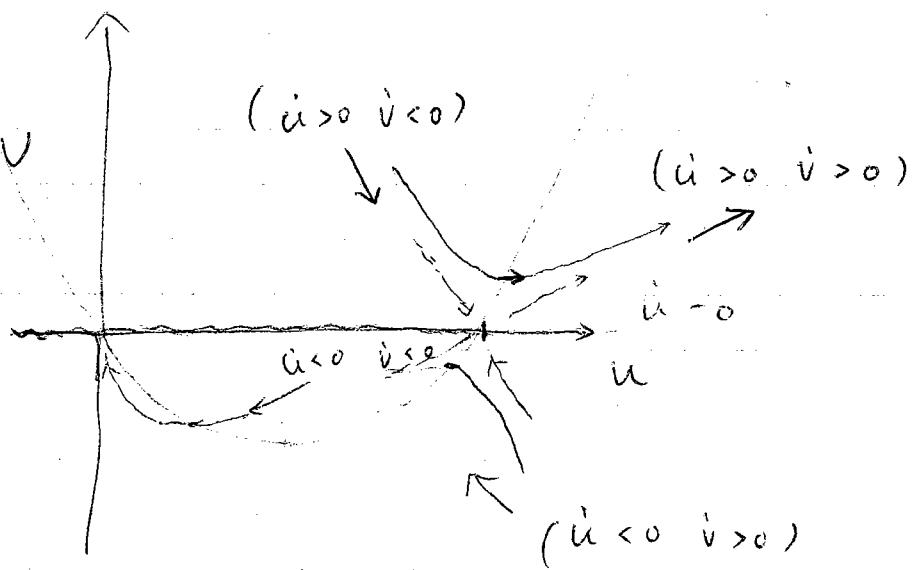
$$u = u(x-ct) = u(z)$$

$$-c \frac{du}{dz} = \frac{d^2 u}{dz^2} + u(1-u)$$

$$\dot{u} = v$$

$$\dot{v} = -cv - u(1-u)$$

phase plane analysis



$$\dot{u} = 0 \rightarrow v = 0 \quad \text{null-cline}$$

$$\dot{v} = 0 \quad v = -\frac{1}{c}u(1-u)$$

stability analysis

$$J = \begin{bmatrix} \frac{\partial \dot{u}}{\partial u} & \frac{\partial \dot{u}}{\partial v} \\ \frac{\partial \dot{v}}{\partial u} & \frac{\partial \dot{v}}{\partial v} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2u-1 & -c \end{bmatrix}$$

evaluated at $(0, 0)$

$$J = \begin{bmatrix} 0 & 1 \\ -1 & -c \end{bmatrix} \quad \text{Tr} = -c \quad \Delta = 1$$

$$\lambda_{1,2} = \frac{\text{Tr} \pm \sqrt{\text{Tr}^2 - 4\Delta}}{2} = \frac{-c \pm \sqrt{c^2 - 4}}{2}$$

$(0, 0)$ is stable node $c^2 > 4$

stable spiral $c^2 < 4$

evaluated at $(1, 0)$

$$J = \begin{bmatrix} 0 & 1 \\ 1 & -c \end{bmatrix} \quad \text{Tr} = -c \quad \Delta = -1$$

$$\lambda_{1,2} = \frac{-c \pm \sqrt{c^2 + 4}}{2} \quad \lambda_1 > 0 \quad \lambda_2 < 0$$

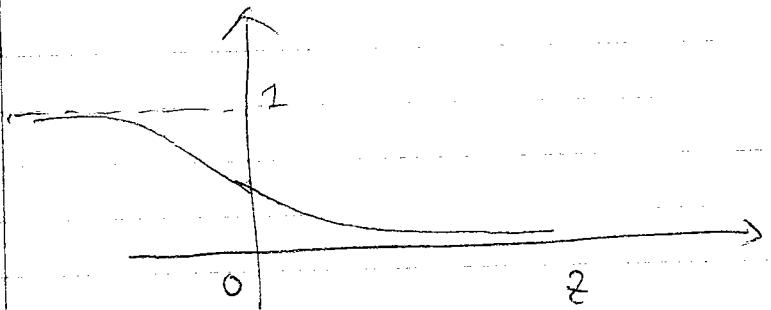
saddle point

when $(0, 0)$ is stable spiral, solution
unphysical as α becomes
negative

when $(0, 0)$ is stable node

there is one unique trajectory
connecting $(1, 0) \rightarrow (0, 0)$

$u(2)$



solution
for the
wave front

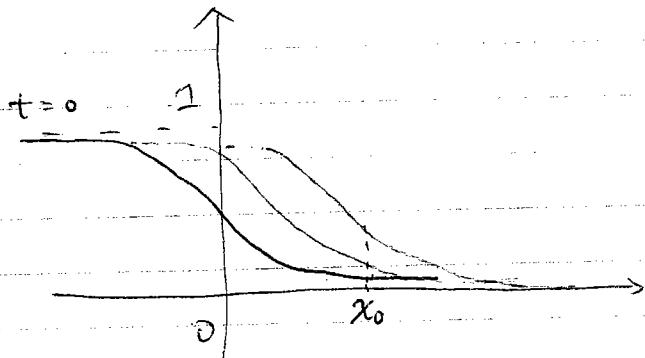
* minimum wave speed

$$c > 2$$

in term of original parameter

$$c > 2\sqrt{RD}$$

traveling wave



Simple argument for wave speed

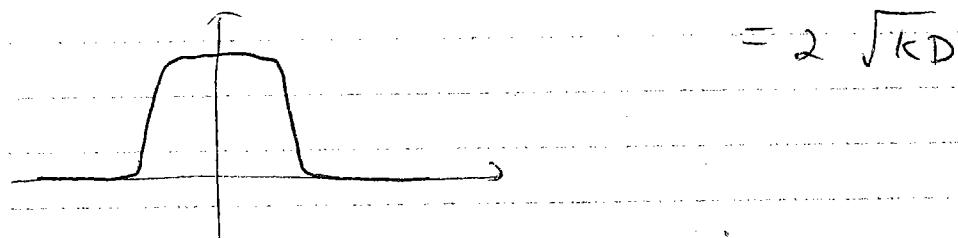
time it takes to grow a
wave front $x_0 \rightarrow u \approx k$

$$\sim \frac{1}{k}$$

when $u(x_0) \sim \frac{1}{z}$
the new wave front diffused $\propto \sqrt{\frac{D}{k}}$
wave speed $\sqrt{\frac{D}{R}} \cdot \frac{1}{k} \sim \sqrt{DK}$

\Rightarrow dependence of wave speed
on initial conditions

if initially only a finite
domain $u = 1, \rightarrow c = C_{\min}$



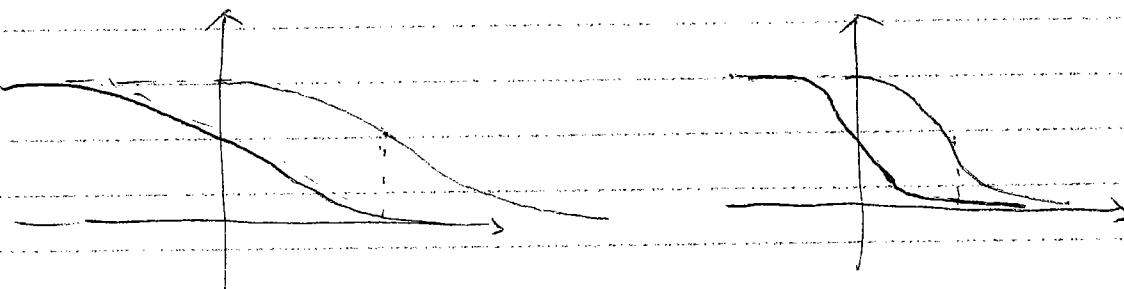
if initially $u(x, 0) \sim Ae^{-ax}$
and $a < 1$

$u(x, t) = Ae^{-a(x-ct)}$ for
the wave front
ignore nonlinear term

$$\frac{\partial u}{\partial t} = u + \frac{\partial^2 u}{\partial x^2}$$

$$ca = 1 + a^2 \quad c = a + \frac{1}{a}$$

flatter wave, faster speed



reaction-diffusion eq. are
widely used for modeling waves
e.g. with growth term

$$f(u) = \alpha u(1-u)(u-c)$$

model Ra waves

△ Fitzhugh-Nagumo eq.
to model action-potential
propagation in a nerve axon